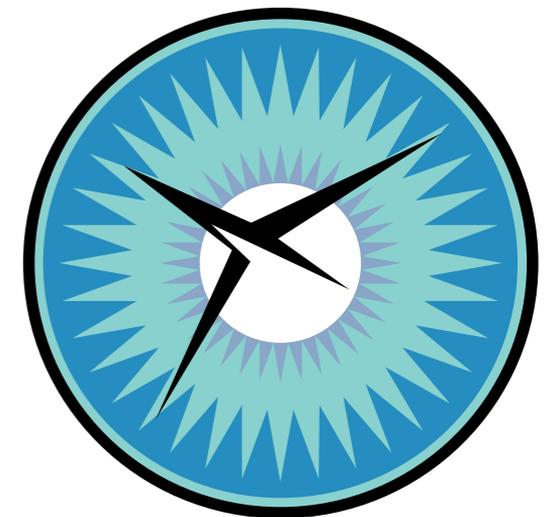


Hyperbolic Navier-Stokes Method for High-Reynolds-Number Boundary-Layer Flows

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National Institute of Aerospace

83rd NIA CFD Seminar, March 7, 2017



A Greatest Tip for Healthier Life

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“If you suffer from high blood pressure/cholesterol/sugar, lose weight, and you’ll be healthier.”

[1] Blackburn G. (1995). Effect of degree of weight loss on health benefits. *Obesity Research* 3: 211S-216S

[2] “Clinical Guidelines on the Identification, Evaluation, and Treatment of Overweight and Obesity in Adults”:
http://www.nhlbi.nih.gov/guidelines/obesity/ob_gdlns.pdf



Great, but doesn’t tell us how to reduce weight.....



“How to lose weight?”

*Approaches are not always non-intuitive:
eat breakfast, drink water, turn off TV, etc.*

A Greatest Tip in Healthier CFD



***“If your CFD code doesn’t work,
add more artificial viscosity, and it’ll work.”***

Increase Q!

$$\Phi(\mathbf{u}_L, \mathbf{u}_R) = \frac{1}{2} (\mathbf{f}_L + \mathbf{f}_R) - \frac{1}{2} \underline{\mathbf{Q}} (\mathbf{u}_R - \mathbf{u}_L)$$

Artificial viscosity / Dissipation / High-frequency damping



“How, and how much to add?”

Many different approaches:

***Artificial viscosity, Riemann solvers, artificial upwinding (FVS),
large edge-term contribution, compact viscous stencil, etc.***

Hyperbolic Navier-Stokes

Since JCP2007

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HNS20 [AIAA 2016-1101](#)

$$\begin{aligned}\operatorname{div}(\rho \mathbf{v}) &= \operatorname{div} \mathbf{r}, \\ \operatorname{div}(\rho \mathbf{v} \otimes \mathbf{v}) + \operatorname{grad} p - \operatorname{div} \boldsymbol{\tau} &= 0, \\ \operatorname{div}(\rho \mathbf{v} H) - \operatorname{div}(\boldsymbol{\tau} \mathbf{v}) + \operatorname{div} \mathbf{q} &= 0, \\ -\operatorname{grad} \mathbf{v} + \mathbf{g} / \mu_v &= 0, \\ \operatorname{grad} \left(\frac{T}{\gamma(\gamma - 1)} \right) + \mathbf{q} / \mu_h &= 0, \\ -\operatorname{grad} \rho + \mathbf{r} / \nu_\rho &= 0.\end{aligned}$$

Gradient variables

$$\nabla \rho_j = \frac{\mathbf{r}_j}{\nu_\rho},$$

$$\nabla \mathbf{v}_j = \frac{\mathbf{g}_j}{(\mu_v)_j},$$

$$\nabla T_j = -\gamma(\gamma - 1) \frac{\mathbf{q}_j}{(\mu_h)_j}.$$

Refs. (3D HNS):

[AIAA 2016-3969](#)

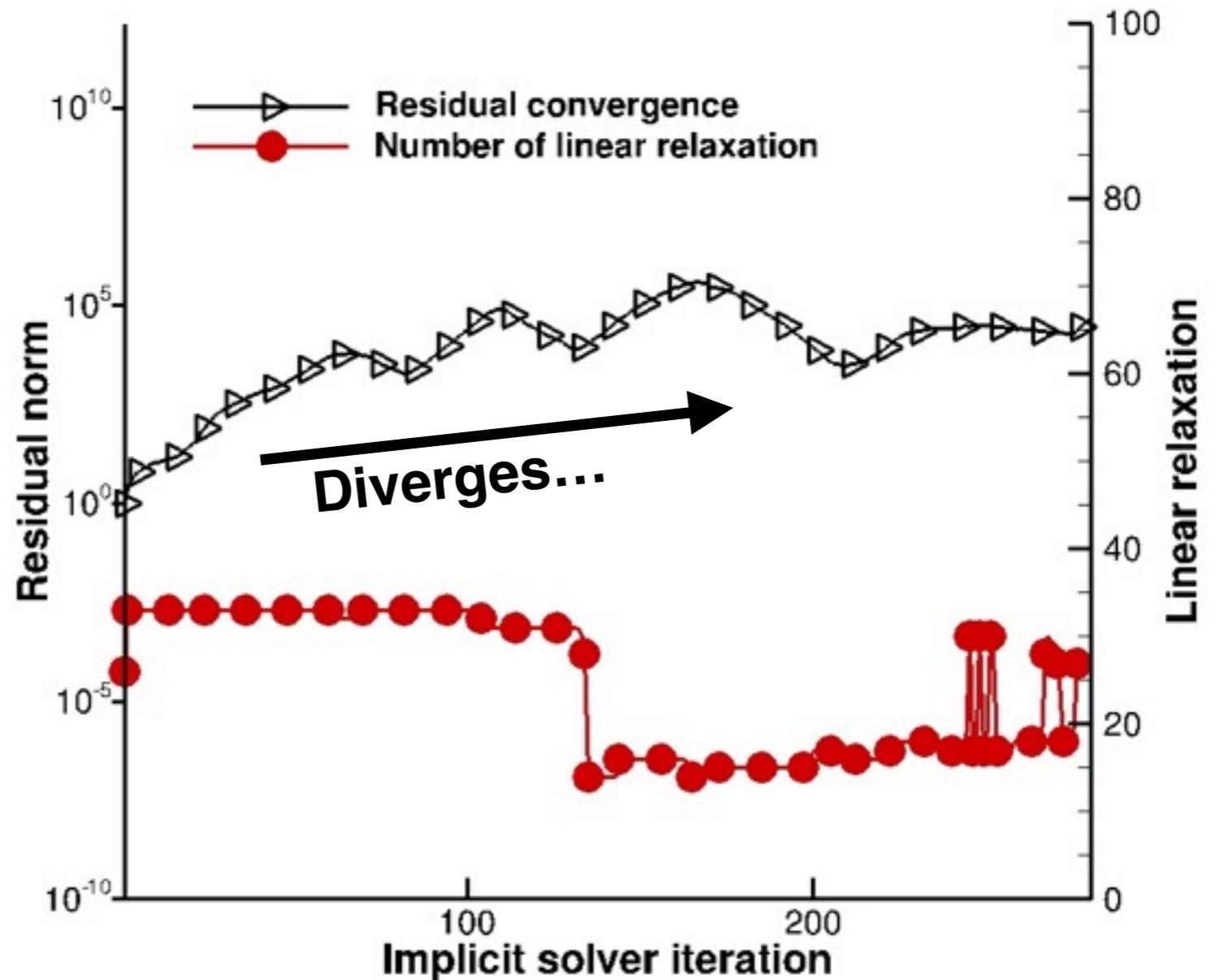
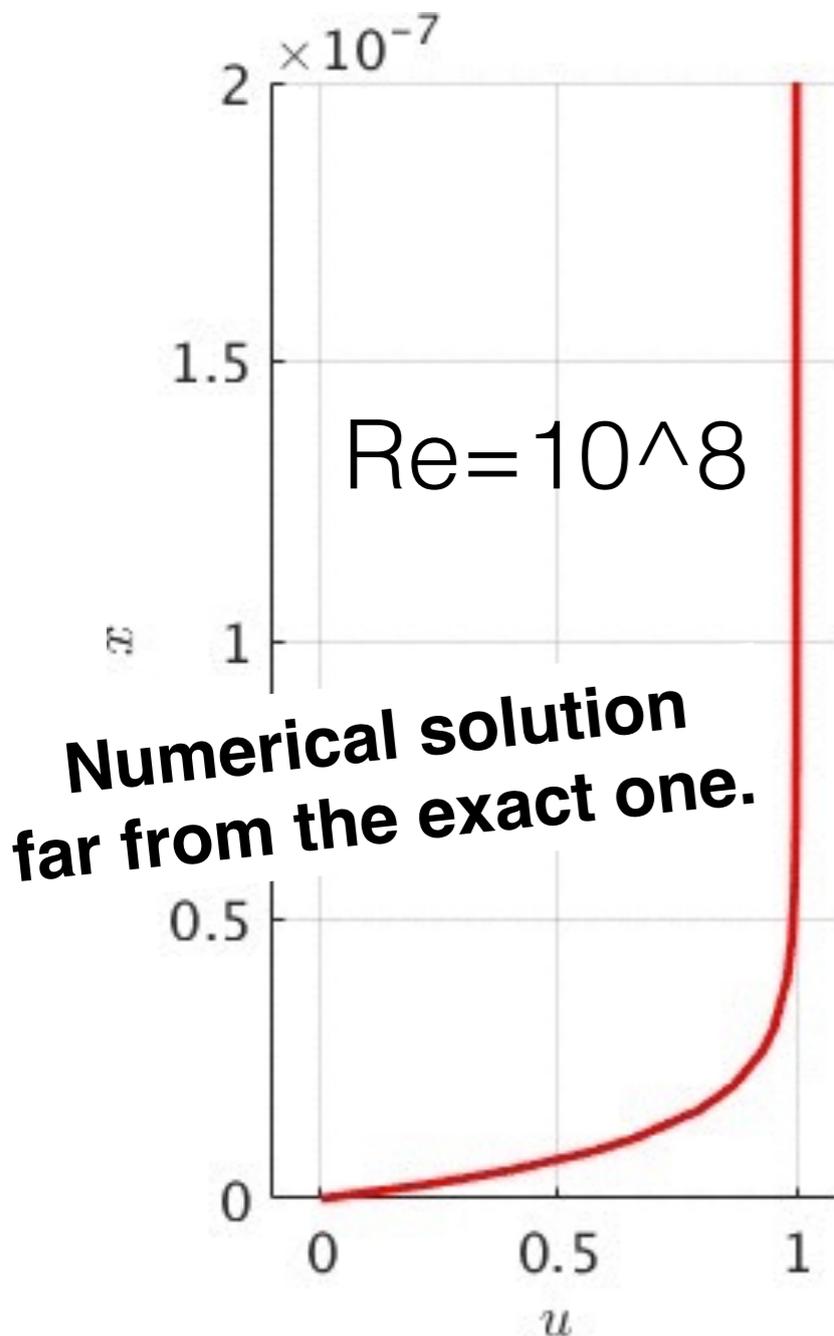
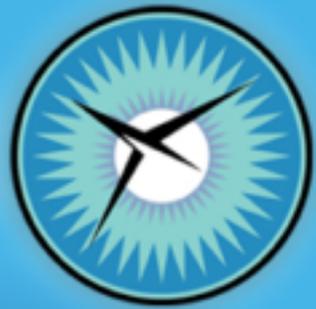
[AIAA 2016-1101](#)

- Simplified viscous discretization/solver
- Improved convergence
- Accurate gradients on irregular grids
- Higher-order inviscid approximation

Website:

hiroakinishikawa.com/fohsm/

Inaccuracy and Divergence



Serious problem for practical viscous-flow application...

No problem in inviscid limits; this is a problem for BL.

Just Increase Dissipation!

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*“If your CFD code doesn’t work,
add more artificial viscosity, and it’ll work.”*

Case of Conventional Scheme



Central scheme:
$$a \frac{u_{j+1} - u_{j-1}}{h} - \nu \frac{u_{j+1} - 2u_j + u_{j-1}}{h^2} = 0$$

has the well-known mesh-Re restriction: $Re_h < 2$

Central scheme can be written in the conservative form:

[See cfdnotes.com "Diffusion Scheme for Discontinuous Data" or [CF2011](#)]

$$f_{j+1/2} - f_{j-1/2} = 0$$

where

$$f_{j+1/2} = \frac{1}{2}(f_{j+1} + f_j) - \frac{a}{Re_h}(u_R - u_L)$$

$$f_j = au_j - \nu \frac{u_{j+1} - u_{j-1}}{2h} \quad u_L = u_j + \frac{h}{2} \frac{u_{j+1} - u_{j-1}}{2h}$$

Indicates that central scheme fails by lack of dissipation for $Re_h > 2$.

Typical remedy is to use dissipative advection scheme, e.g., upwind.

Hyperbolic Scheme



Hyperbolic advection-diffusion system:

$$\begin{aligned}\partial_\tau u + \partial_x (au - \nu p) &= 0 \\ (T_r/\nu)\partial_\tau p - \partial_x u &= -p/\nu\end{aligned}$$

Relaxation time:

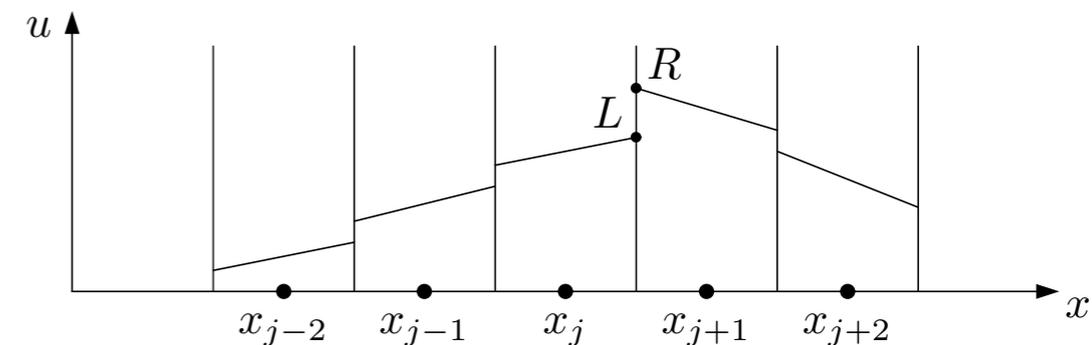
$$T_r = L_r^2/\nu$$

Length scale (JCP2007,2013):

$$L_r = L_d \equiv \frac{1}{2\pi}$$

Node-centered FV with upwind flux:

$$\Phi(\mathbf{u}_L, \mathbf{u}_R) = \frac{1}{2} (\mathbf{f}_L + \mathbf{f}_R) - \frac{1}{2} \mathbf{Q} (\mathbf{u}_R - \mathbf{u}_L)$$



Dissipation matrix $|\mathrm{dF}/\mathrm{dU}|$ can be constructed (JCP2010), but it is too complicated for the Navier-Stokes...

Dissipation Matrix



Simplified approach ([AIAA2011-3043](#)):

Advective Jacobian + Diffusive Jacobian:

$$\mathbf{Q} = |\mathbf{A}^a| + |\mathbf{A}^d| = \begin{bmatrix} |a| & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} a_v & 0 \\ 0 & a_v \end{bmatrix} \quad a_v : \text{Diffusion wave speed}$$

The approach has been successfully extended to 3D NS ([AIAA 2016-1101](#)), but the convergence problem was encountered for High-Re BL.

Note: Extra dissipation from advection scheme only helps the first equation.

Nakashima (Cradle) and Baty (U of Strasbourg) pointed out that L_r needs to be reduced for high-Re boundary layers. **Good approach.**

Questions: *How much to reduce? What does it mean?*

**Exploring various approaches,
we found one that works for us...**

Forget the dissipation, and look at the error.

1D Boundary Layer Problem



Balanced High-Re Limit

$$a\partial_x u = \nu\partial_{xx}u$$

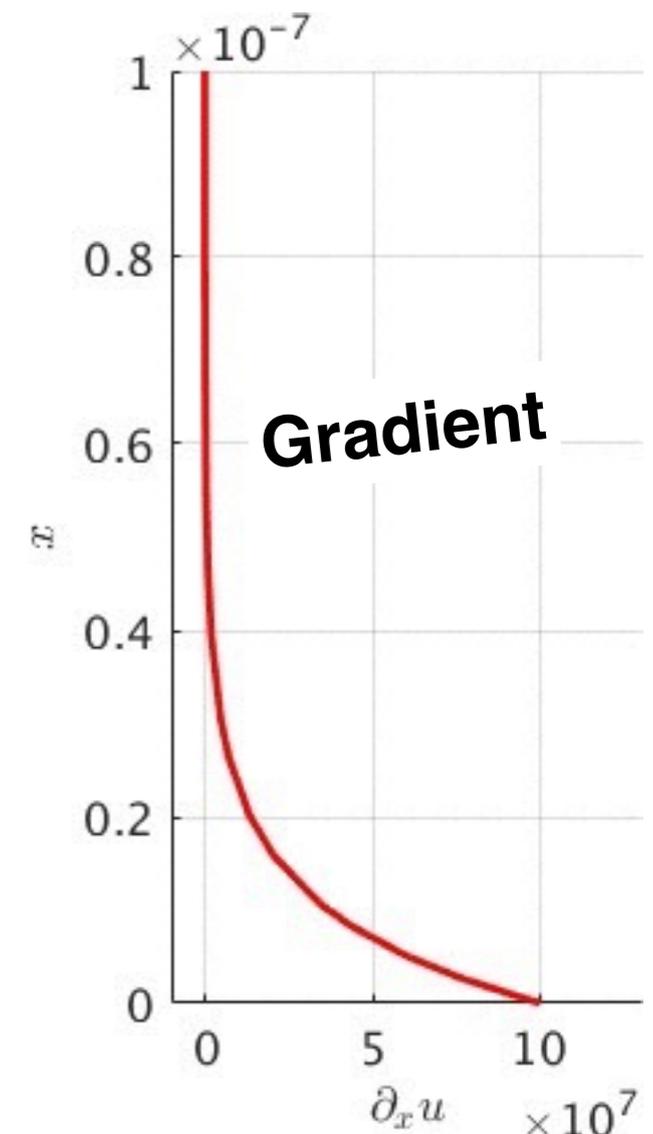
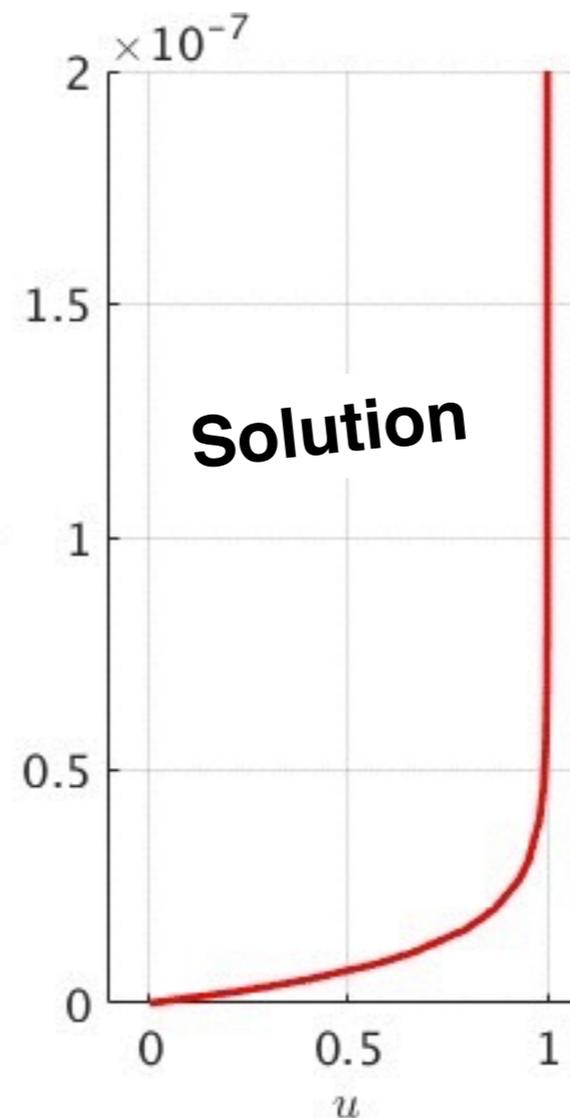
Exact solution:

$$u(x) = \frac{1 - \exp(Re_x)}{1 - \exp(Re)}$$
$$= \underbrace{K_1(1)} + \underbrace{K_2 \exp(Re_x)}$$

two modes

Reynolds number based on x :

$$Re_x = \frac{ax}{\nu}$$



Modal Analysis for 1st-Order Scheme



$$\text{Residual}(\mathbf{u}_j = \mathbf{U}c^j) \longrightarrow \mathbf{M}\mathbf{U} = 0 \longrightarrow \det(\mathbf{M}) = 0$$

$$c_1 = 1$$

$$c_2 = \frac{2Re_{Lr}^2 + 2Re_{Lr}Re_h + 2Re_{Lr} + Re_h + \sqrt{(Re_h + 2Re_{Lr})(4Re_{Lr}^2Re_h + 4Re_{Lr}Re_h + 2Re_{Lr} + Re_h)}}{2(Re_{Lr}^2 + 2Re_{Lr} + Re_h)}$$

$$c_3 = \frac{2Re_{Lr}^2 + 2Re_{Lr}Re_h + 2Re_{Lr} + Re_h - \sqrt{(Re_h + 2Re_{Lr})(4Re_{Lr}^2Re_h + 4Re_{Lr}Re_h + 2Re_{Lr} + Re_h)}}{2(Re_{Lr}^2 + 2Re_{Lr} + Re_h)}$$

where

$$Re = \frac{a}{\nu}, \quad Re_{Lr} = \frac{aL_r}{\nu}, \quad Re_{Ld} = \frac{aL_d}{\nu}, \quad Re_h = \frac{ah}{\nu}$$

Accurate modes are $c_1=1$ and c_2 :

$$c_2^j = c_2^{\frac{x}{h}} = \exp(Re_x) \left(1 - \frac{Re_{Lr}^2 + Re_{Lr} + 1}{2Re_{Lr}} Re_x Re_h + O(h^2) \right)$$

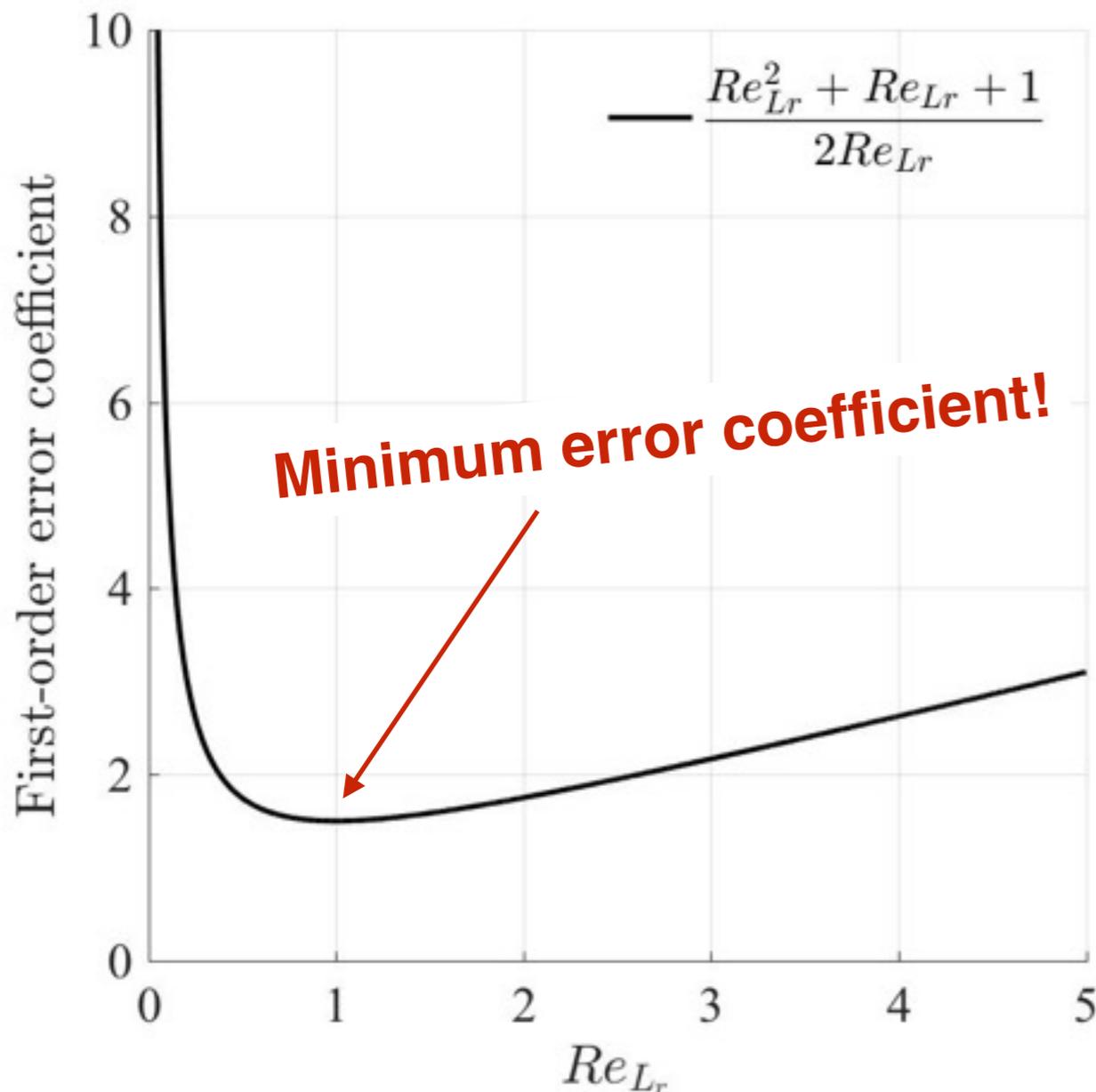
1st-order error

“Oh, no... This is a problem...”

Minimize the error



For $Re = \frac{a}{\nu} \rightarrow \infty \longrightarrow Re_{Lr} = L_r Re \rightarrow \infty$ if $L_r = L_d \equiv \frac{1}{2\pi}$



Minimum error at

$$\frac{\partial}{\partial Re_{Lr}} \left(\frac{Re_{Lr}^2 + Re_{Lr} + 1}{2Re_{Lr}} \right) = 0$$

The solution is

$$Re_{Lr} = 1$$

which means

$$L_r = \frac{1}{Re}$$

Dissipation retained



$$L_r = L_d \equiv \frac{1}{2\pi} \longrightarrow a_v = \frac{\nu}{L_r} = 2\pi\nu = \frac{2\pi a}{Re} \rightarrow 0$$
$$Q = |\mathbf{A}^a| + |\mathbf{A}^d| = \begin{bmatrix} |a| & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} a_v & 0 \\ 0 & a_v \end{bmatrix}$$

A red arrow points from the top-right element of the second matrix, a_v , to a red '0' at the top right of the slide.

$$L_r = \frac{1}{Re} \longrightarrow a_v = \frac{\nu}{L_r} = \nu Re = \nu \frac{a}{\nu} = a$$
$$Q = |\mathbf{A}^a| + |\mathbf{A}^d| = \begin{bmatrix} |a| & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} a_v & 0 \\ 0 & a_v \end{bmatrix}$$

Dissipation from hyperbolic diffusion stays finite for large Re , and acts as additional dissipation to fight against high-frequency errors.

Iterative Convergence (2nd-order)

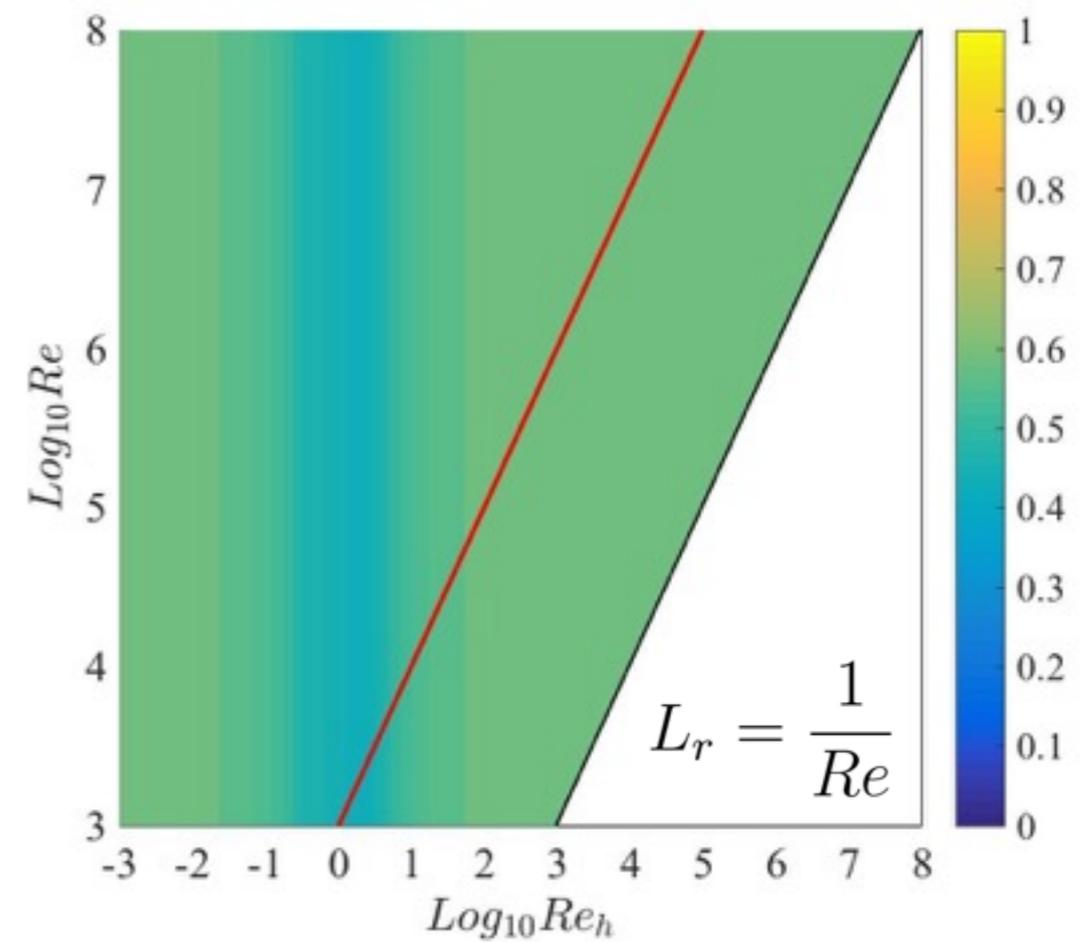
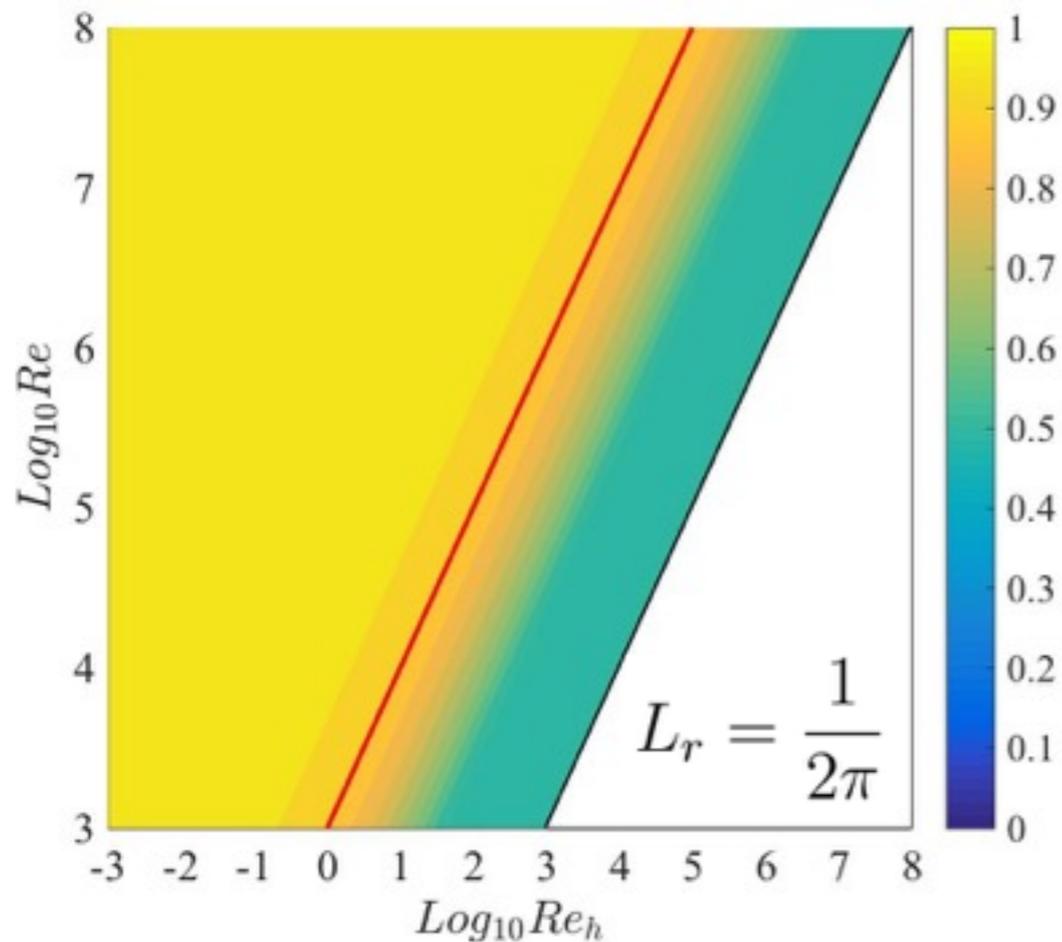


Implicit solver

$$\begin{aligned} \mathbf{U}^{k+1} &= \mathbf{U}^k + \Delta \mathbf{U} \\ \mathbf{J} \Delta \mathbf{U} &= -\mathbf{Res}(\mathbf{U}^k) \end{aligned}$$

Fourier transform

$$\mathbf{U}_0^{k+1} = (\mathbf{I} - \mathbf{J}^{-1} \mathbf{R}) \mathbf{U}_0^k$$



Extra dissipation also resolves convergence issue.

Greatest tip works!



*“If your CFD code doesn’t work,
add more artificial viscosity, and it’ll work.”*

“Add more dissipation by $Lr = 1/Re!$ ”

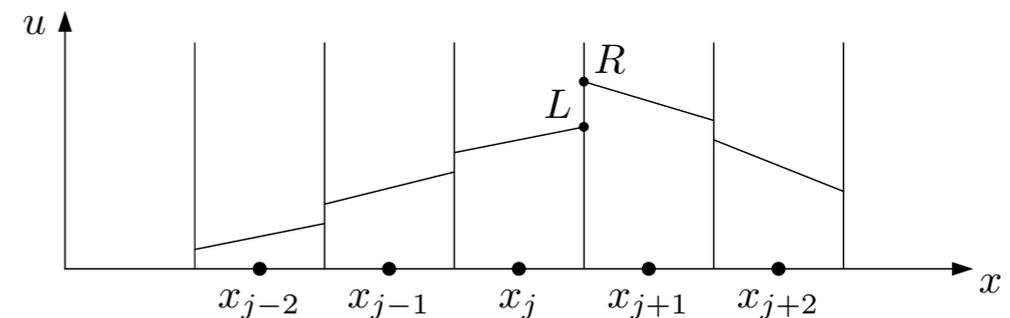
$$\begin{bmatrix} |a| & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} a_v & 0 \\ 0 & a_v \end{bmatrix}$$

Second-Order Schemes



Linear reconstruction to the face:

$$\mathbf{u}_L = \mathbf{u}_j + \frac{\Delta x_j}{2} (\partial_x \mathbf{u})_j, \quad \mathbf{u}_R = \mathbf{u}_{j+1} - \frac{\Delta x_{j+1}}{2} (\partial_x \mathbf{u})_{j+1},$$



Scheme-I: Linear LSQ gradient for all.

$$(\partial_x \mathbf{u})_j = \frac{\sum_{k \in \{k_j\}} (\mathbf{u}_k - \mathbf{u}_j)(x_k - x_j)}{\sum_{k \in \{k_j\}} (x_k - x_j)^2}$$

Scheme-IQ: Compact quadratic LSQ gradient for u .

AIAA 2016-3969

$$(\partial_x u)_j = \frac{\sum_{k \in \{k_j\}} \left(u_k - u_j - \frac{1}{2\nu} (\partial_x p)_j (x_k - x_j)^2 \right) (x_k - x_j)}{\sum_{k \in \{k_j\}} (x_k - x_j)^2}$$

Scheme-II:
 $(\partial_x u)_j = p_j / \nu$

Issues remain.
See paper.

Scheme-IQ achieves 3rd-order accuracy in advection limit.

Second-Order Correction



Modal analysis gives:

$$(c - 1) [K_3 c^3 + K_2 c^2 - K_1 c + K_0] = 0,$$

where

$$K_3 = Re_{Lr} (Re_{Lr} + 3) c^3, \quad K_2 = Re_{Lr}^2 + (7 - 4Re_h) Re_{Lr} + 4Re_h,$$
$$K_1 = 5Re_{Lr}^2 + (12Re_h + 7) Re_{Lr} + 4Re_h, \quad K_0 = 3Re_{Lr} (Re_{Lr} - 1).$$

Minimize the number of negative roots:

$$L_r = \frac{K}{Re}, \quad K = \max \left(1, 4Re_h - \frac{7}{2} \right)$$

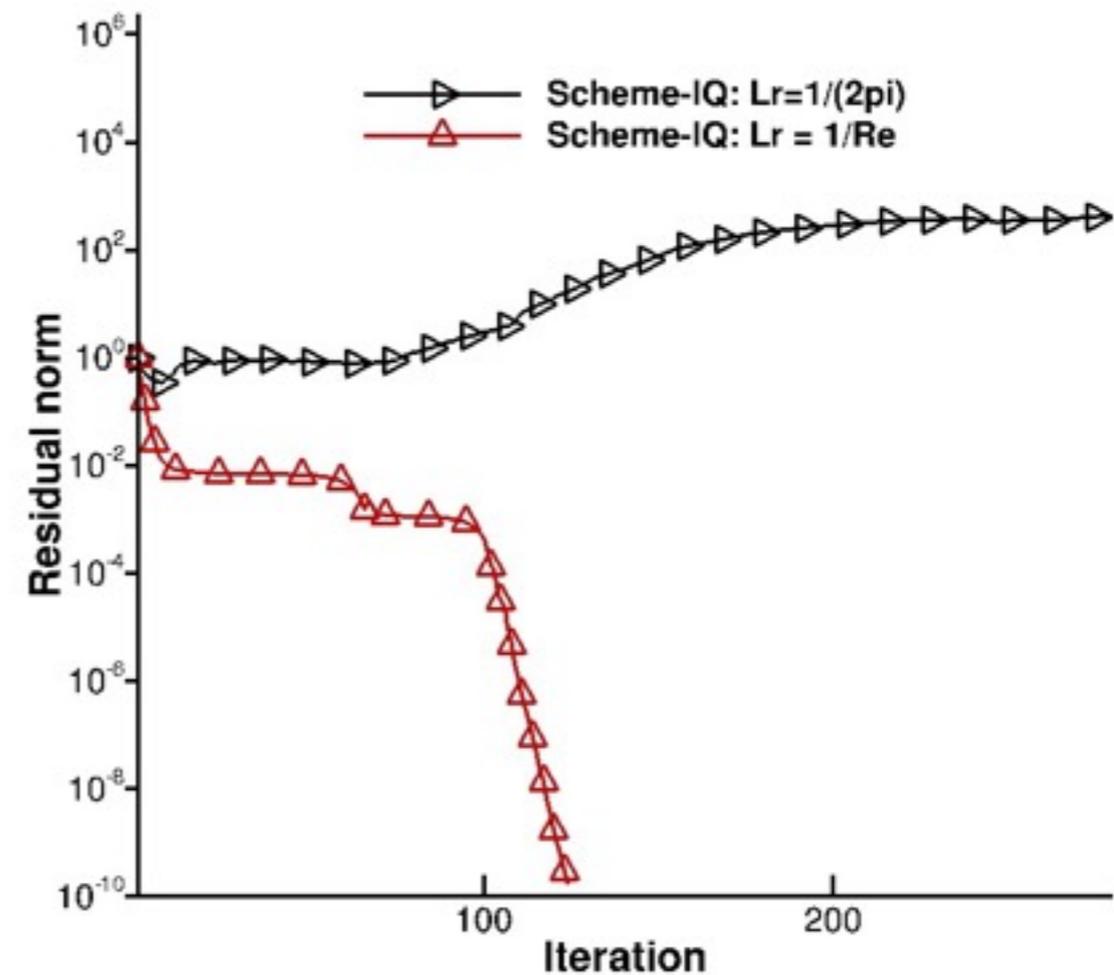
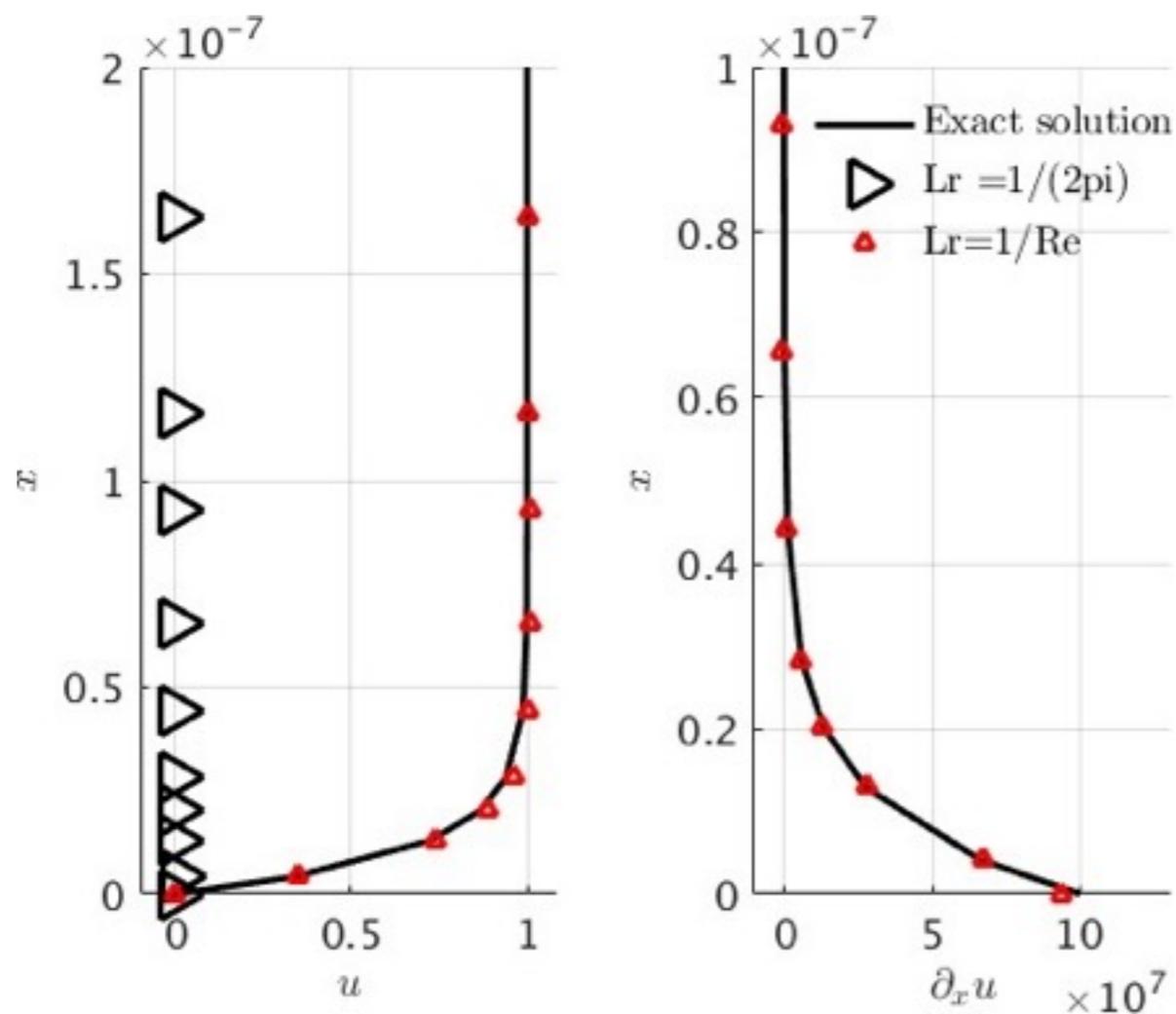
K is the 2nd-order correction to $L_r = 1/Re$, which has been found effective for under-resolved grids.

Results in One Dimension



Re = 100 million.

Scheme-IQ converges rapidly and produce accurate solutions.



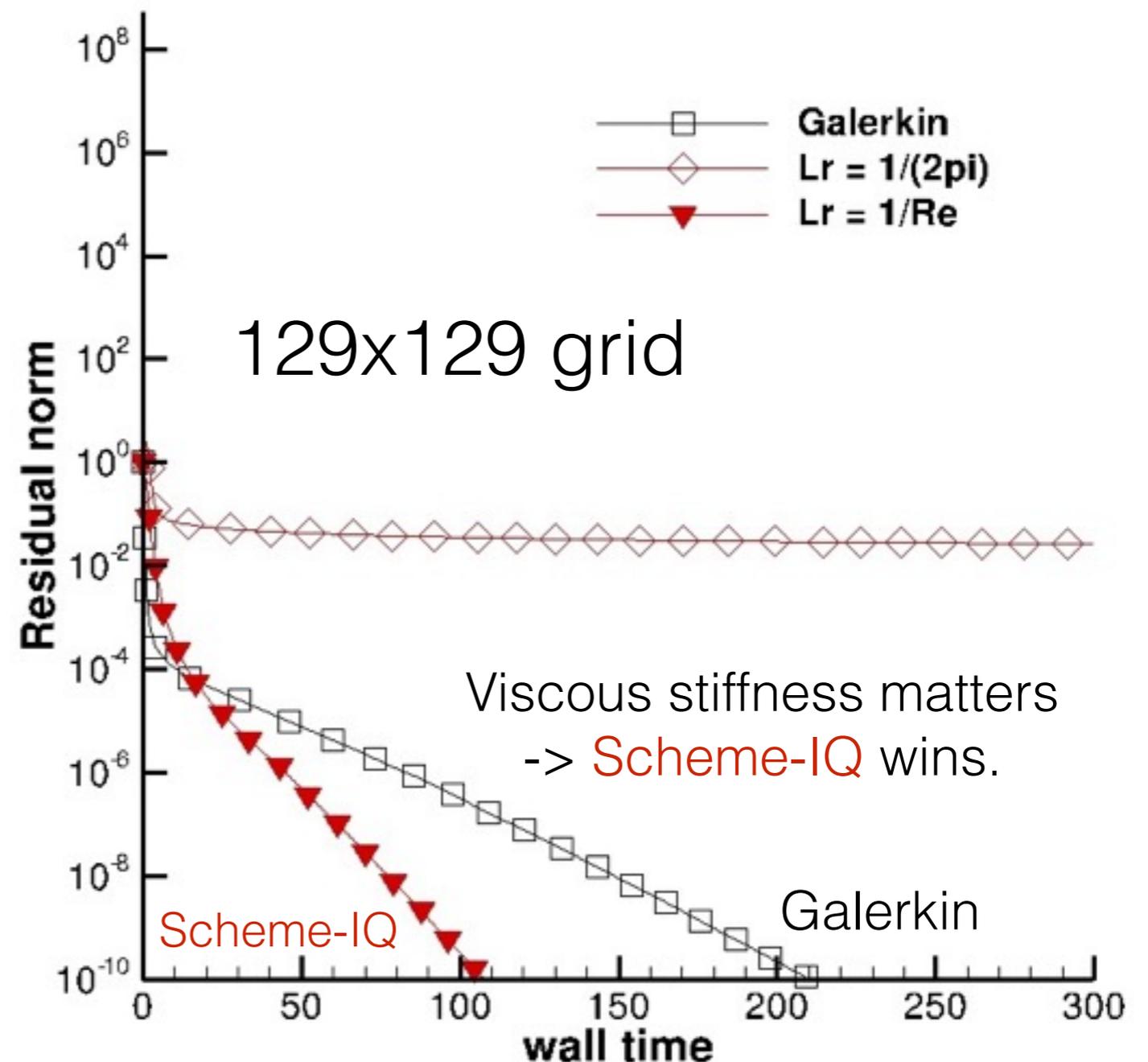
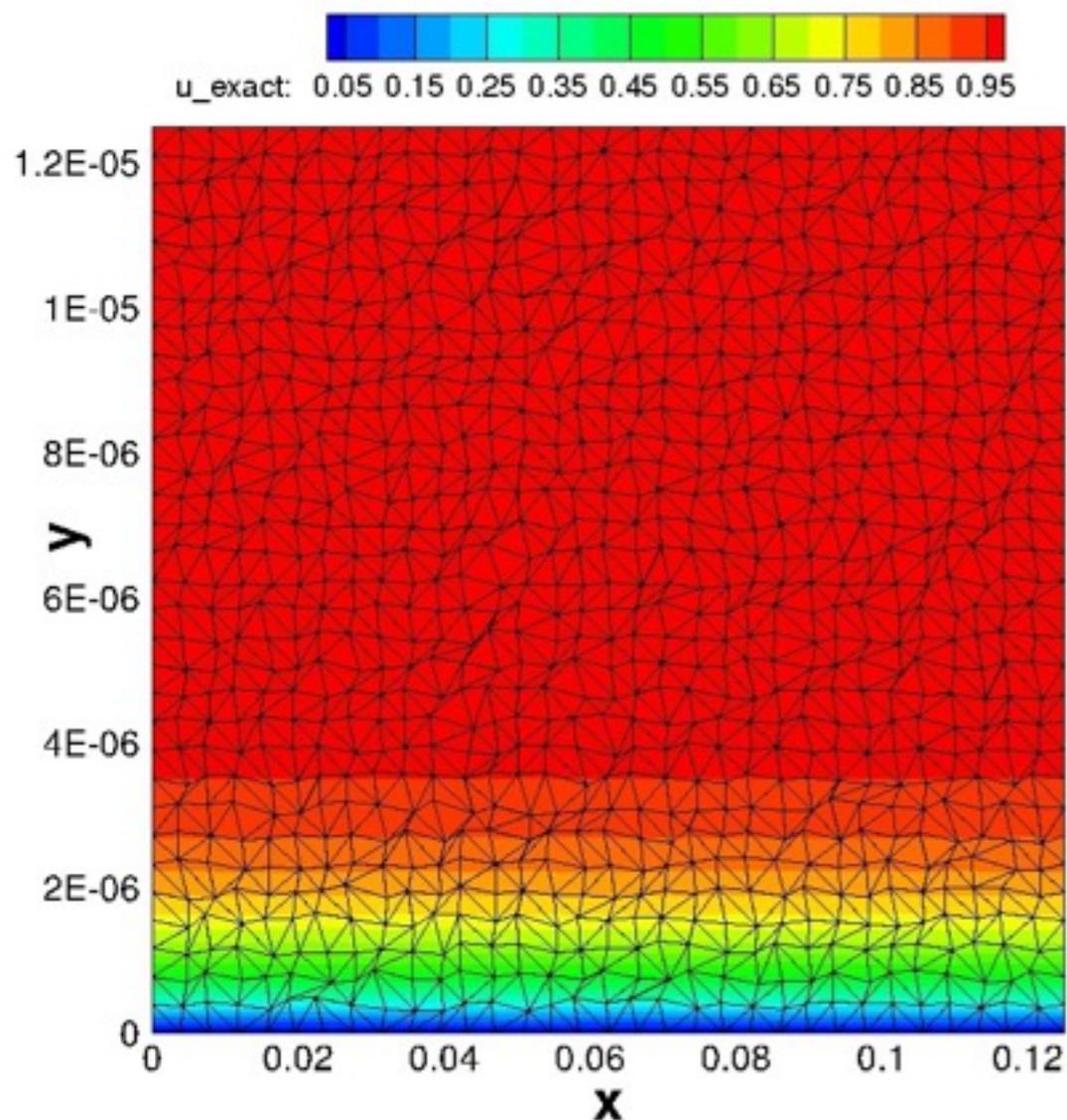
Results for strong/weak BCs and for viscous Burgers in the paper.

Results in Two Dimension

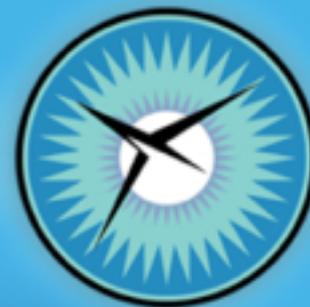


1D BL in a 2D domain. $Re = 1$ million.

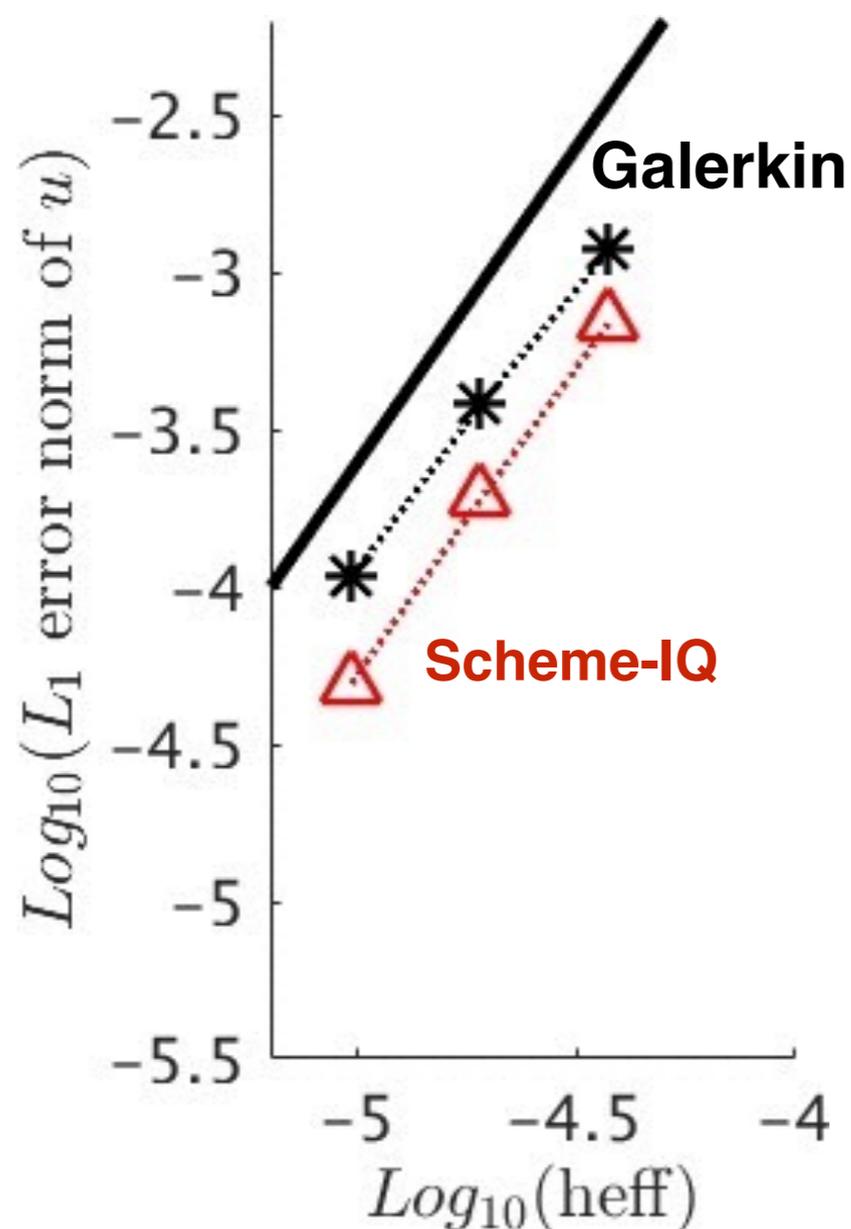
Scheme-IQ converges rapidly and produce accurate solutions.



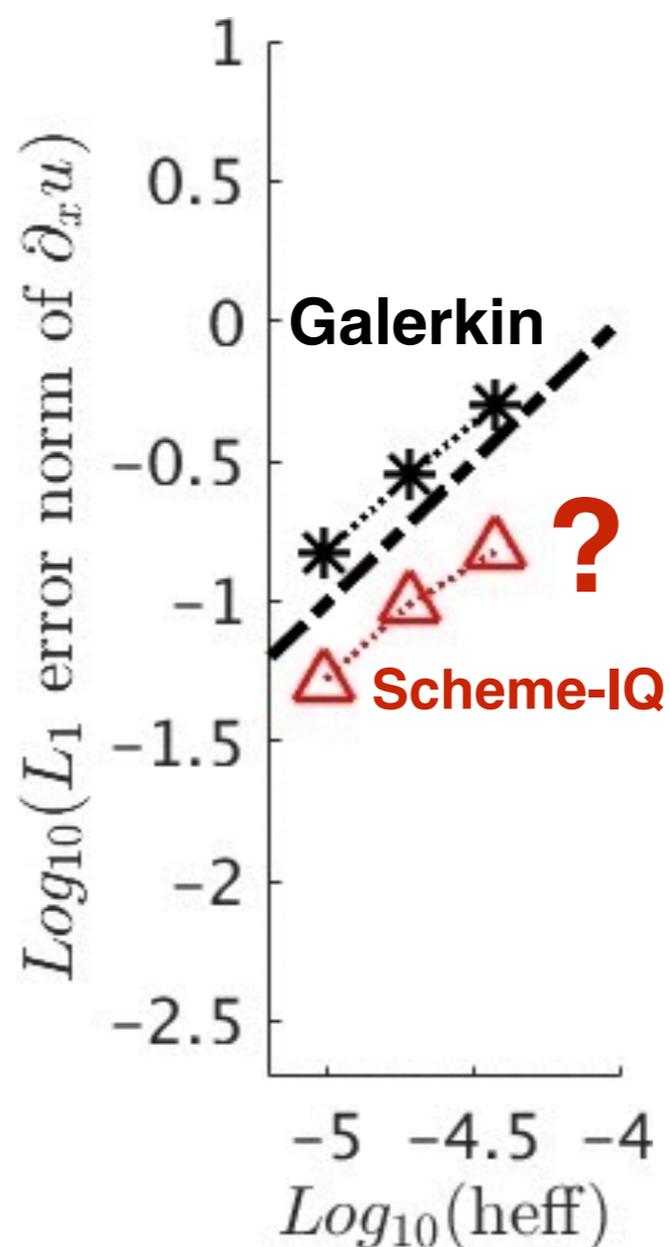
Results in Two Dimension



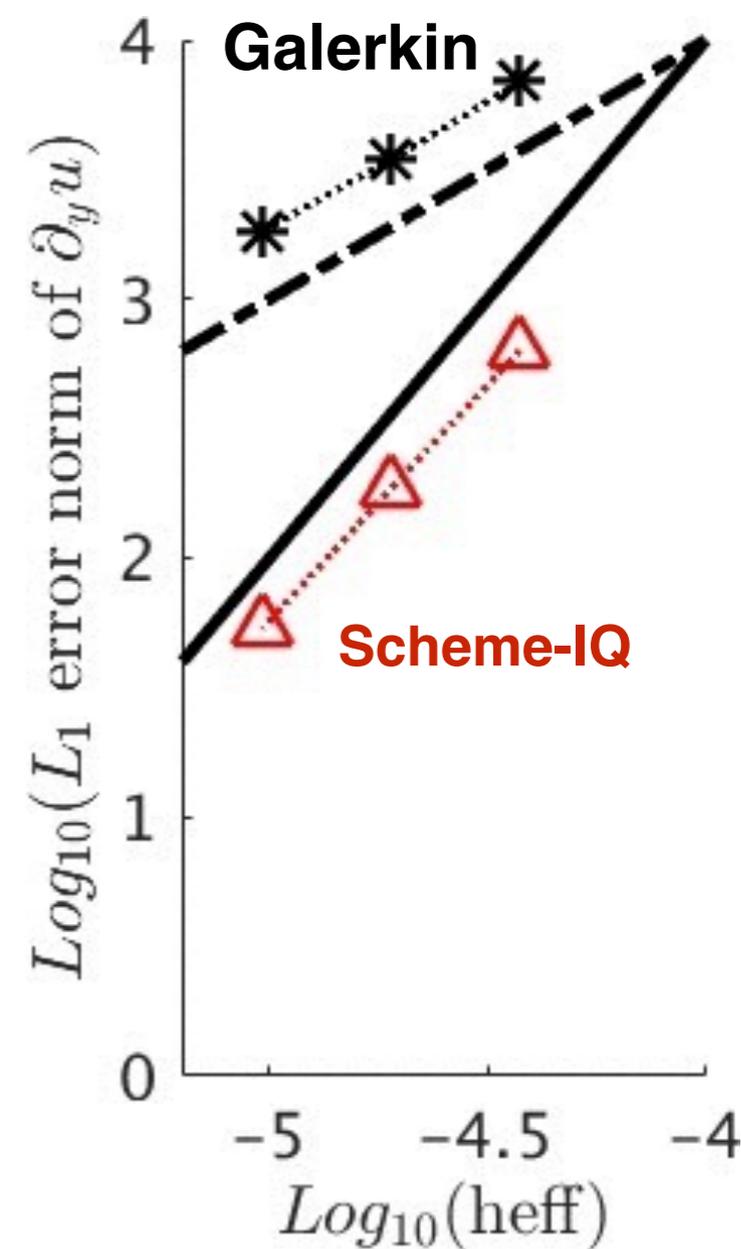
Solution



X-derivative



Y-derivative

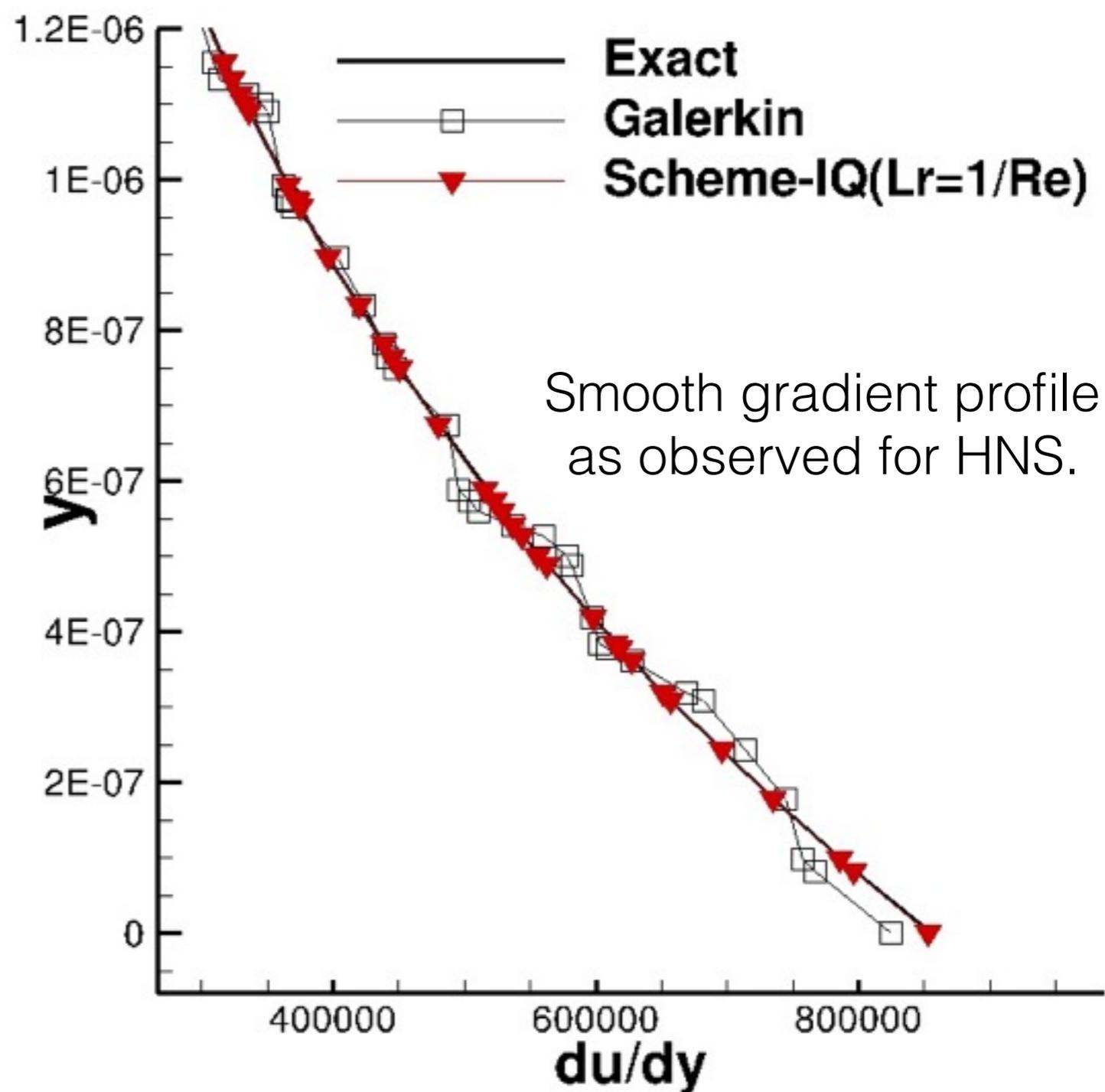
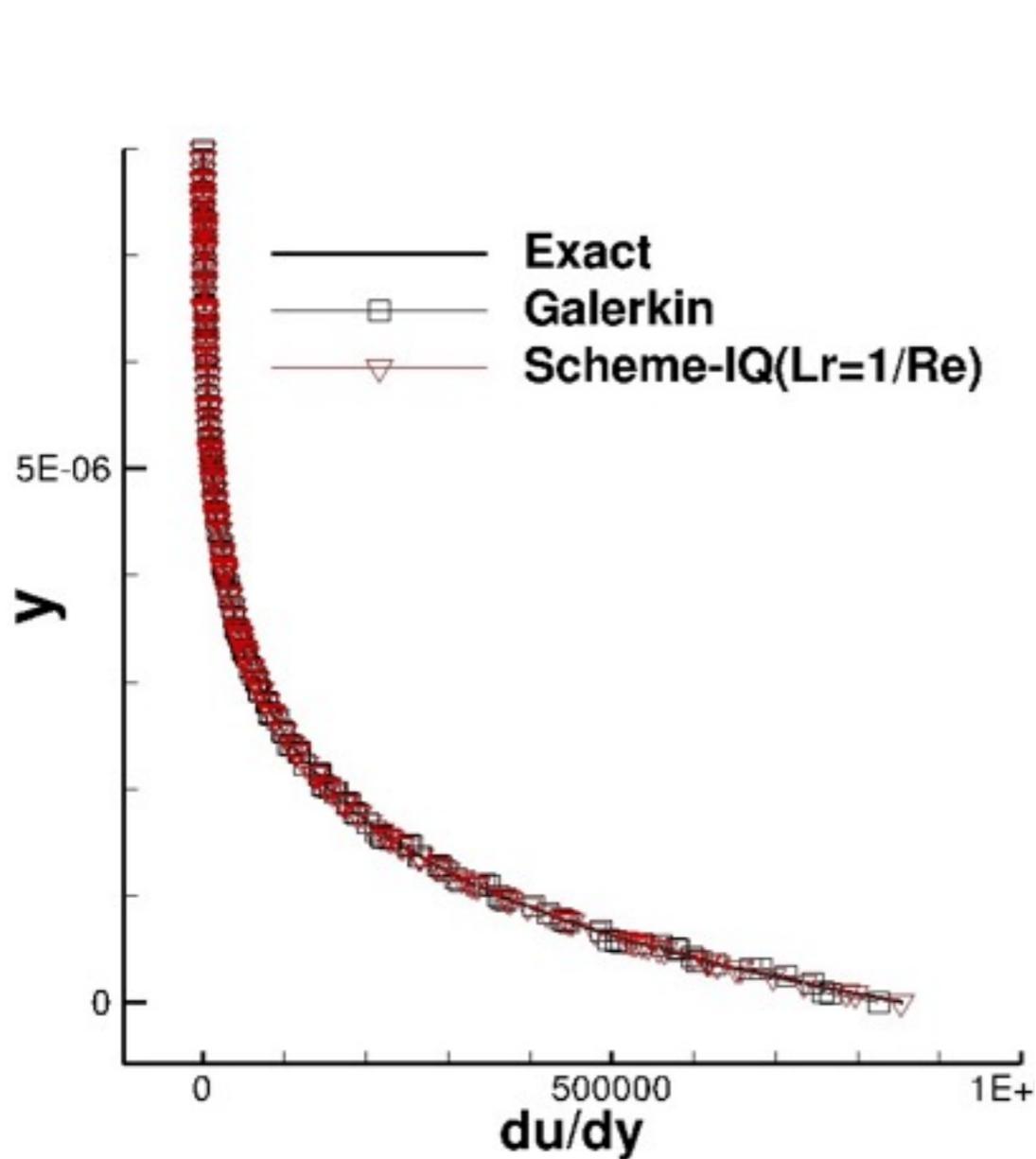


Comparison: Galerkin and Hyperbolic with $Lr=1/Re$.

Results in Two Dimension



Comparison of Gradient (viscous stress)



Extensions to HNS



Three lengths for HNS20: $T_\rho = \frac{L_\rho^2}{\nu_\rho}$, $T_v = \frac{L_v^2}{\nu_v}$, $T_h = \frac{L_h^2}{\nu_h}$

Set $L = 1/Re$ for all in high-Re cases:

$$L_v = \psi(Re_{L_d}^v) L_d, \quad Re_{L_d}^v = \frac{|u| L_d}{\nu_v} \quad L_d \equiv \frac{1}{2\pi}$$

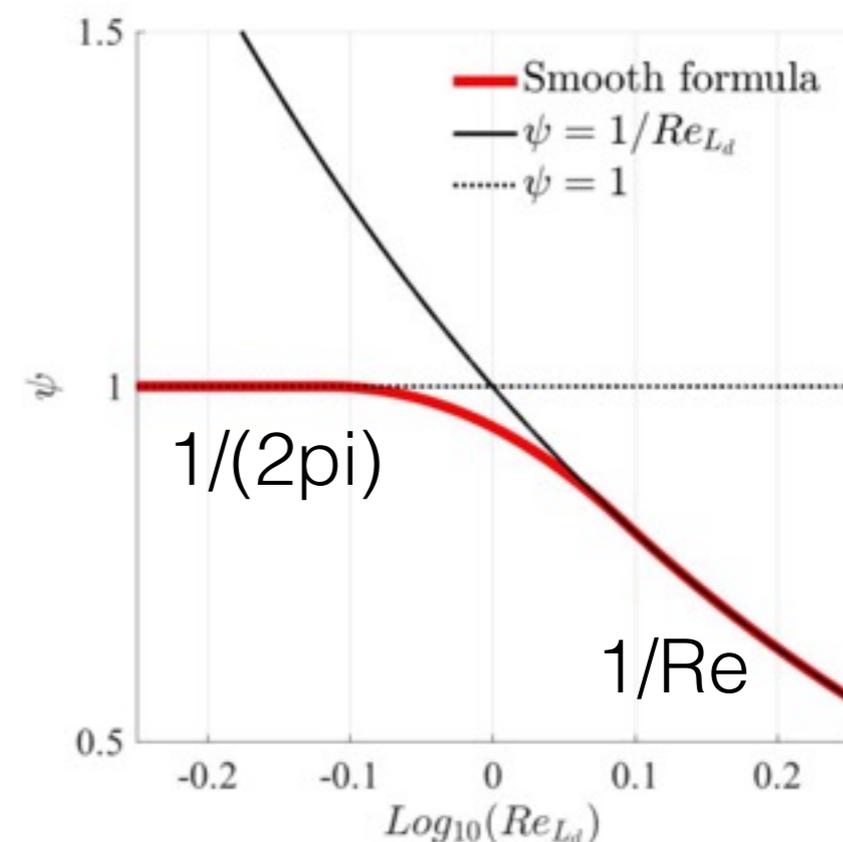
Switching function:

$$\psi(Re_{L_d}^v) = \min\left(1, \frac{K}{Re_{L_d}^v}\right)$$

K: 2nd-order correction for under-resolved grids.

$L = 1/(2\pi)$ for small R

$L = 1/Re$ for large Re.





1. Local Reynolds number

$$\psi(Re_{L_d}^v) = \min \left(1, \frac{K}{\underline{Re_{L_d}^v}} \right)$$

2. Free-stream Reynolds number

$$\psi_{\infty}(Re_{L_d}^{\nu_{\infty}}) = \min \left(1, \frac{K}{\underline{Re_{L_d}^{\nu_{\infty}}}} \right)$$

3. Approximate function

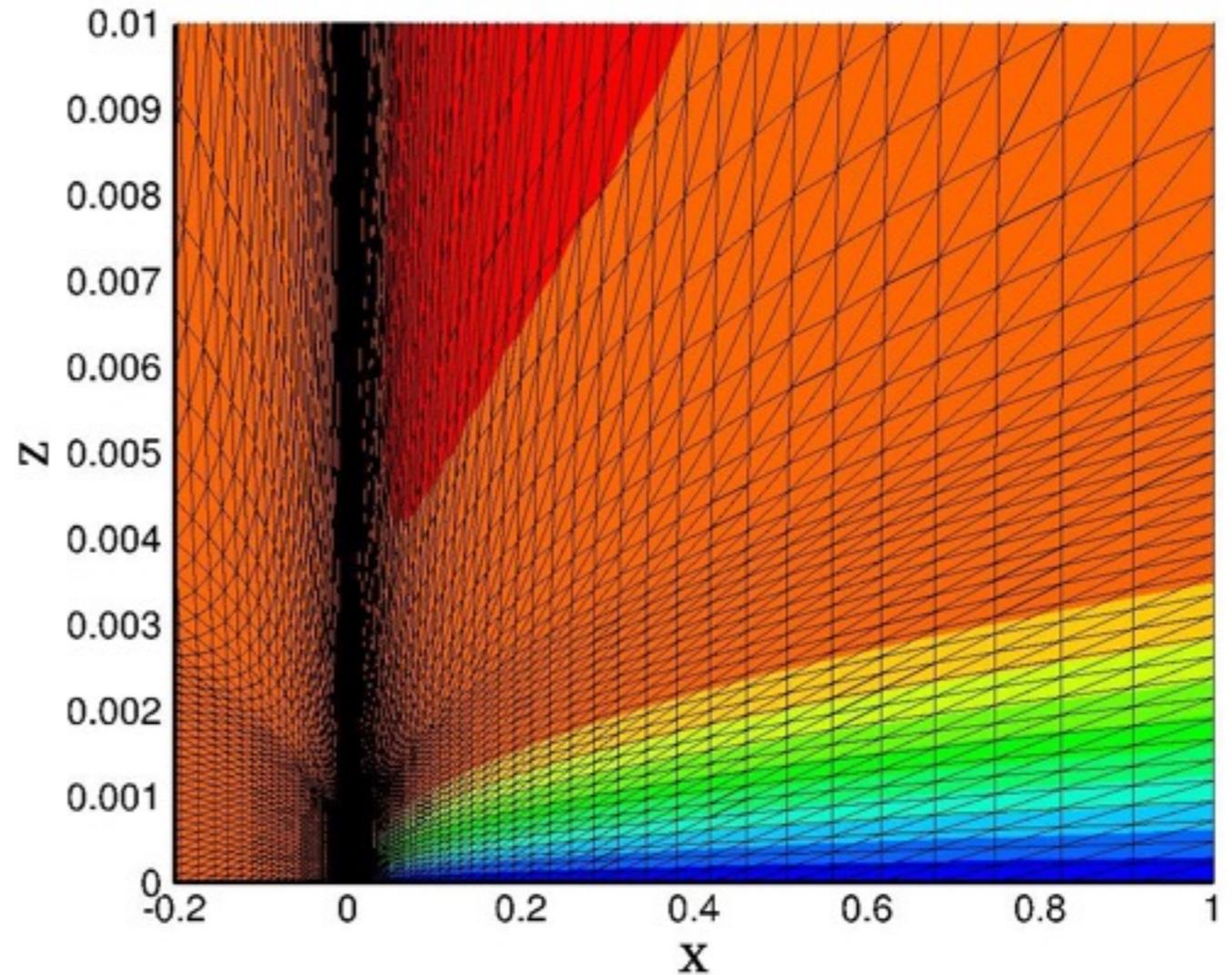
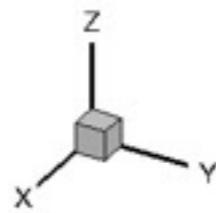
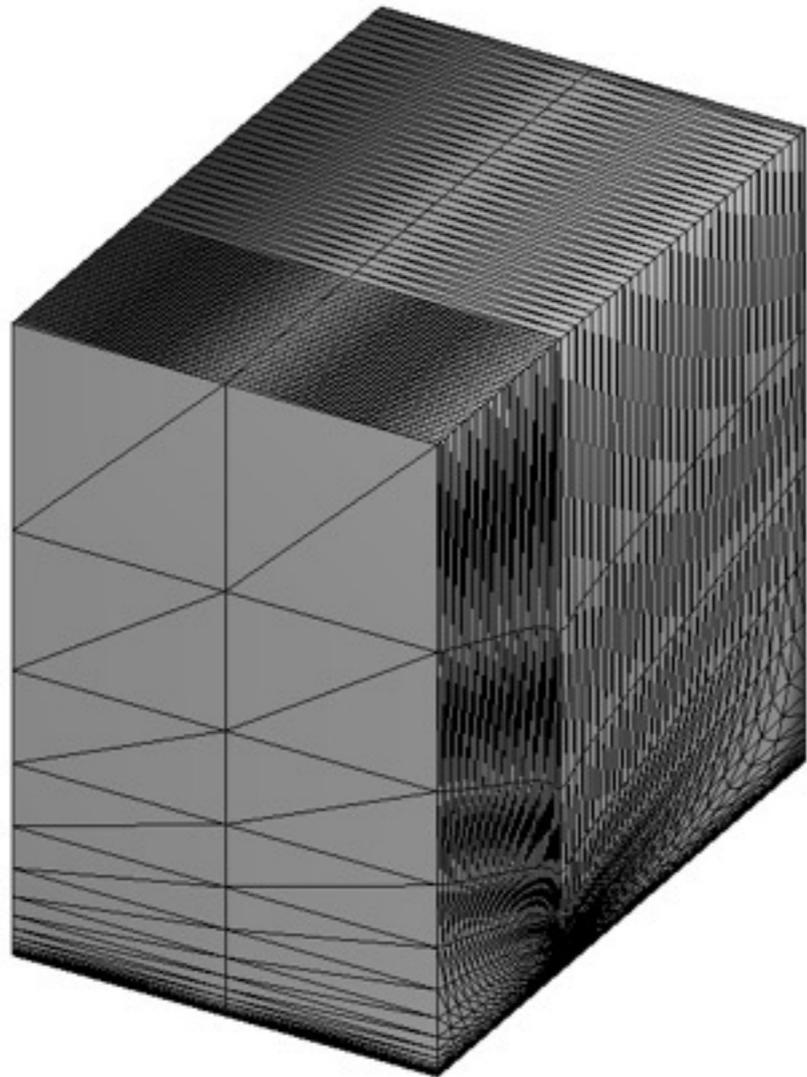
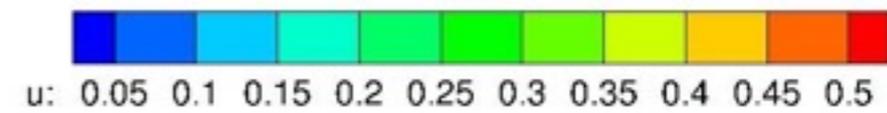
$$\psi(Re_{L_d}^{\nu_{\infty}}) = \frac{1}{\sqrt{Re_{L_d}^{\nu_{\infty}}}}$$

Results for 3D HNS (FUN3D)

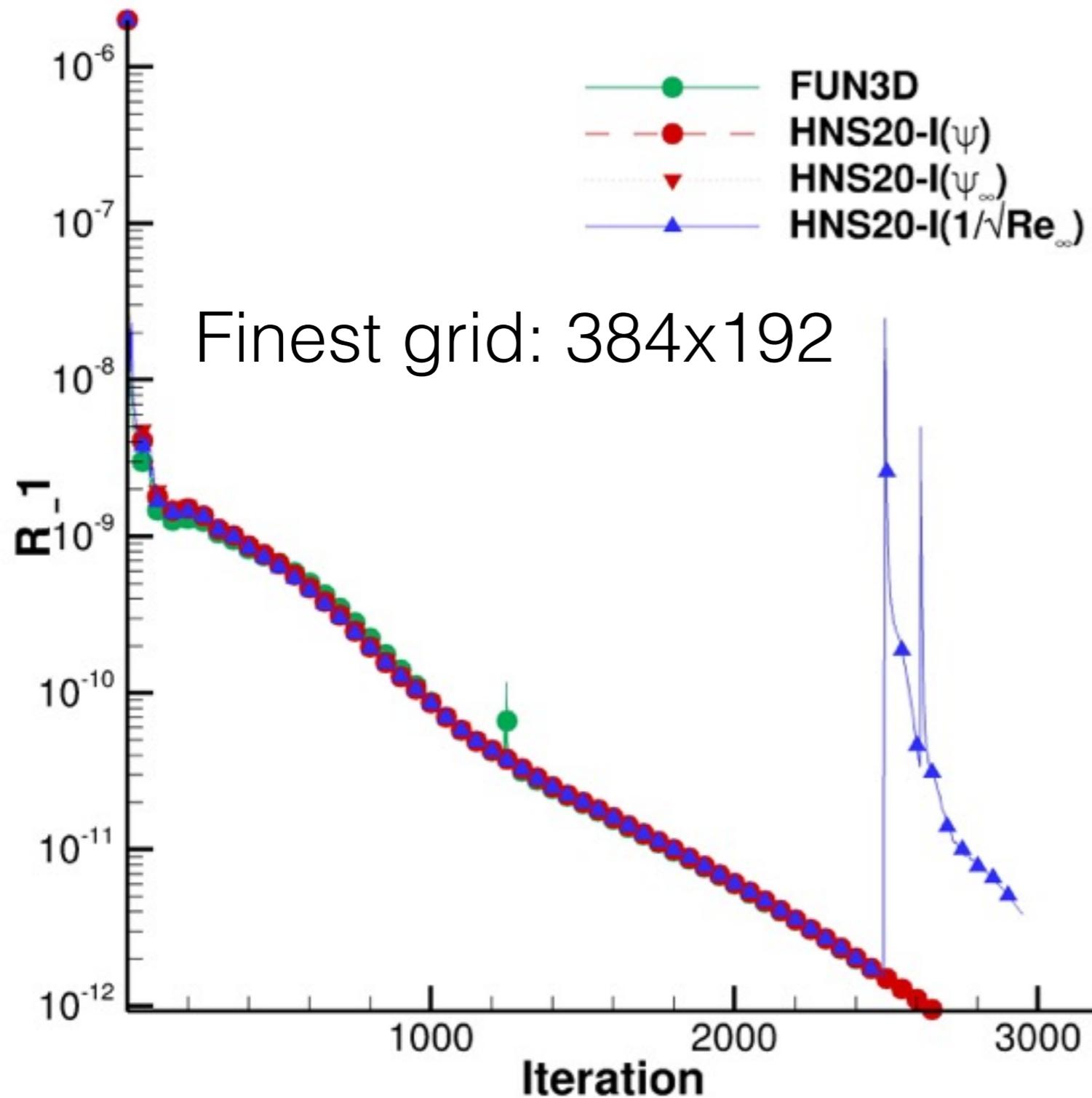
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Laminar flat plate at $Re = 1$ million



Results for HNS

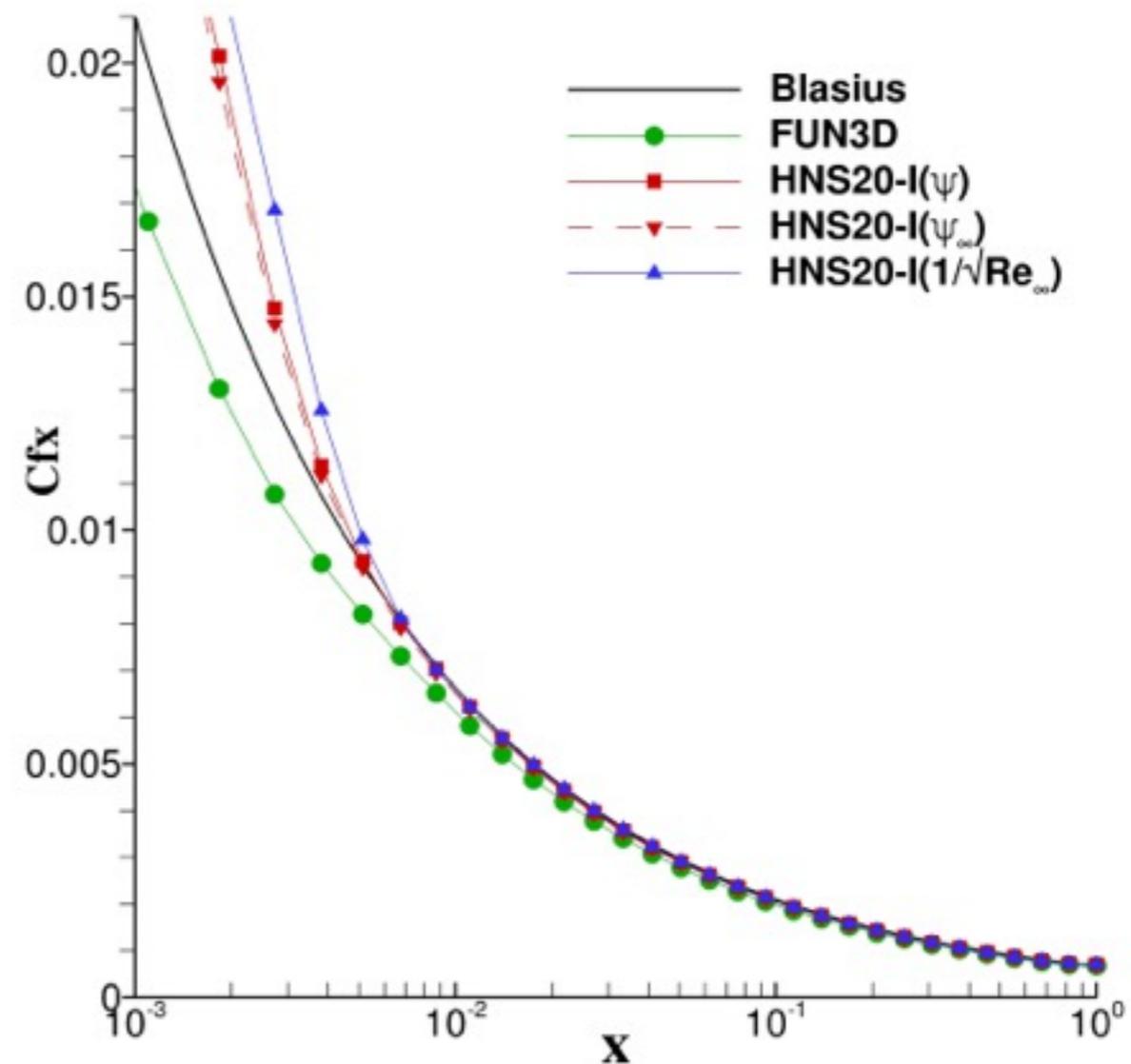
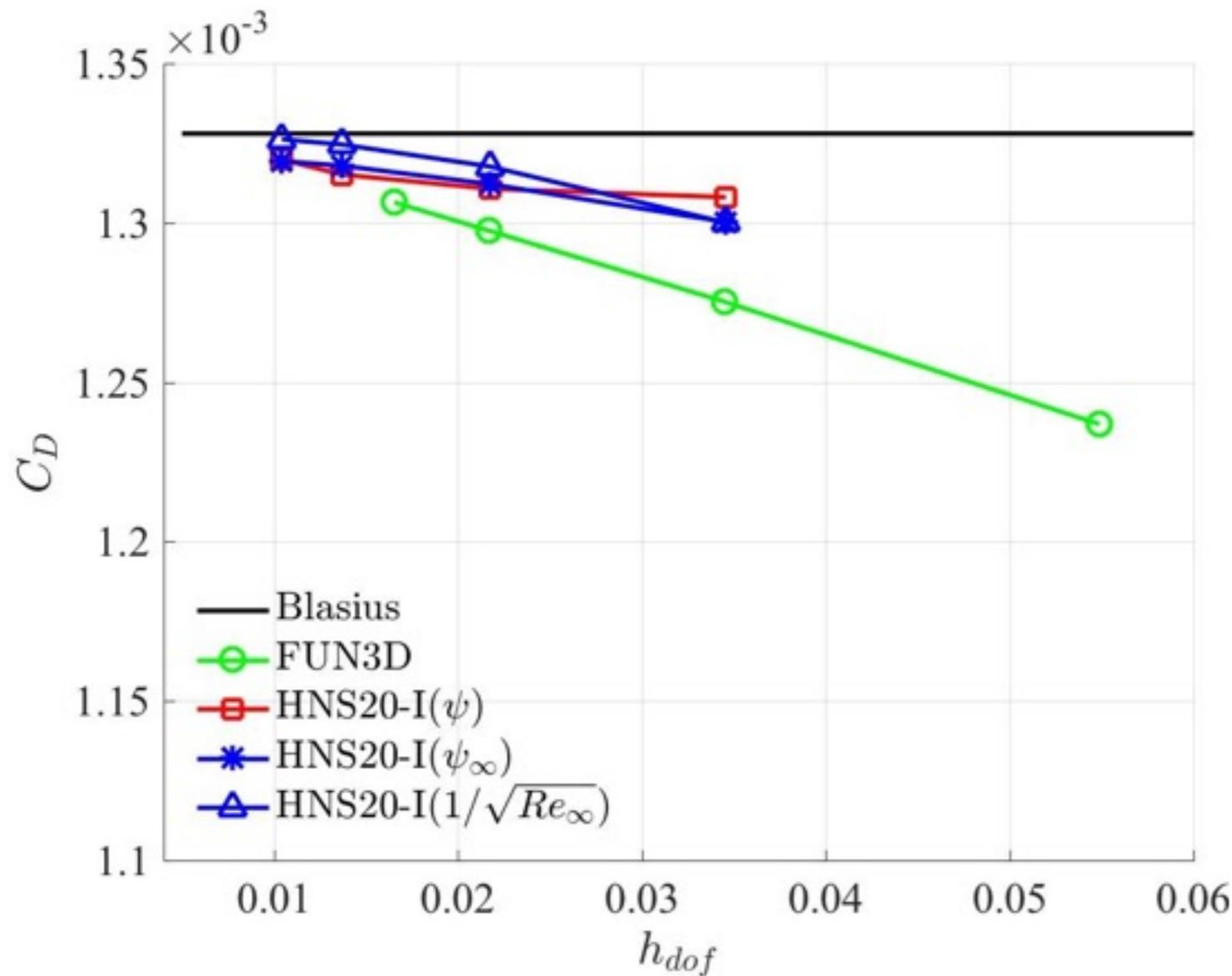


- 4 grids
64x32, 128x64
256x128, 384x192
- 15 linear relaxations.
- CFL = 200
- HNS20 Jacobian with AD.

Results for HNS



64x32



Superior not only in C_D , but also in the local skin friction.

Conclusions



- $L_r = l/Re$ for high- Re boundary-layer flows.

Improves accuracy and iterative convergence.

Dissipation recovered, which vanishes otherwise.

- $L_r = l/Re$ may be evaluated at free-stream for NS.

Simple to implement.

HNS can be made useful for accurate and efficient boundary-layer calculations.

Current and Future work



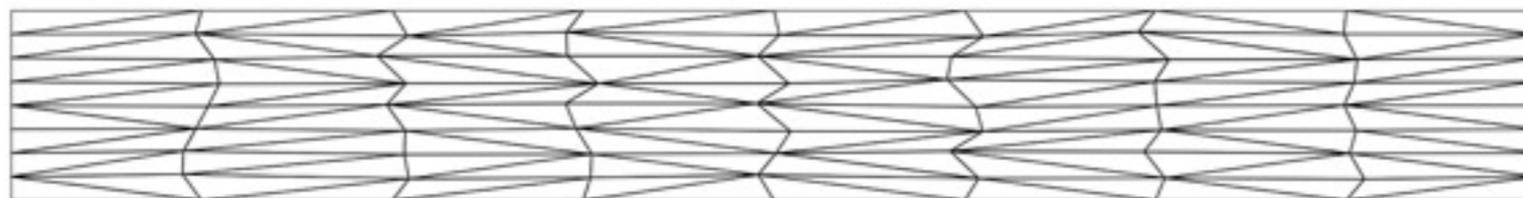
- **Extend HNS20 to high-Re turbulent flows.**

NASA TMR test cases: Hemisphere cylinder, OM6.

- **Issues remain for Scheme-II.** Details in the paper. [AIAA2017-0081](#)

Problems with irregular stretched grids and 3D viscous cases.

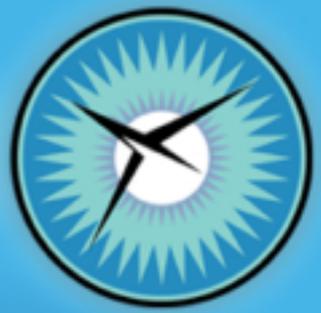
- **Accuracy deterioration in gradient: one-order lower.**



→ gradient in this direction.

A Greatest Tip in CFD

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*“If your CFD code doesn’t work,
add more artificial viscosity, and it’ll work.”*

Keep adding dissipation until it works!

NOTE: I’m just kidding. It’s not that easy at all!